



# *Preprocessing CVS Data for Fine-Grained Analysis*

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# Motivation

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Tom Ball et al. “*If your version control system could talk. . .*”

So, why is my CVS so silent?

1. CVS has limited query functionality and is slow.  
⇒ Copy CVS into a database
2. CVS splits up changes on multiple files.  
⇒ Infer transactions
3. CVS knows only files—but what about functions?  
⇒ Detect fine-grained changes
4. CVS contains unreliable data which is noise.  
⇒ Clean data

Preprocessing is the key to a *talkative* version control system.



# Copy CVS into a Database



```
RCS file: /home/eclipse/org.eclipse.jdt.core/model/org/eclipse/jdt/core/IBuffer.java,v
Working file: ./org.eclipse.jdt.core/model/org/eclipse/jdt/core/IBuffer.java
head: 1.17
branch:
locks: strict
access list:
symbolic names:
```

v_397:	1.16
v_396a:	1.16
...	
v_382:	1.15
JDK_1_5:	1.15.0.2
Root_JDK_1_5:	1.15
v_381:	1.15
...	

Tags	

Files	

Directories	

```
keyword substitution: o
total revisions: 24; selected revisions: 24
description:
```

Branches	

```
-----
revision 1.17
date: 2004/01/13 15:48:42; author: jlnaneluc; state: Exp; lines: +1 -1
Updated copyrights to 2004
```

```
-----
revision 1.16
date: 2003/12/15 16:25:37; author: jlnaneluc; state: Exp; lines: +15 -26
46040
```

```
-----
revision 1.15
date: 2003/05/26 16:13:24; author: pmulet; state: Exp; lines: +5 -1
branches: 1.15.2;
*** empty log message ***
```

```
-----
revision 1.15.2.1
date: 2004/01/12 19:53:11; author: othomann; state: Exp; lines: +15 -26
Merge with HEAD
=====
```

Revisions	



Transactions	

Create *incremental* copies with `cv diff -s` or `cv status`.



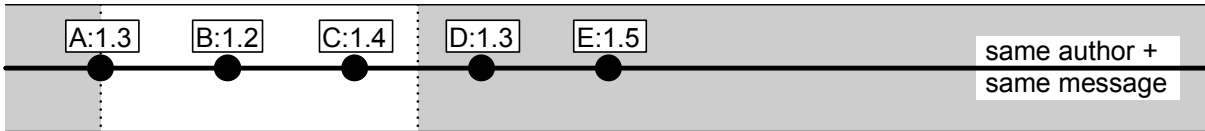


# Infer Transactions: Time Windows

All changes by the same developer, with the same message, made at the “same time” belong to one transaction.

## Fixed Time Window

$$\forall \delta_i : \forall \delta_j : |time(\delta_i) - time(\delta_j)| \leq T$$



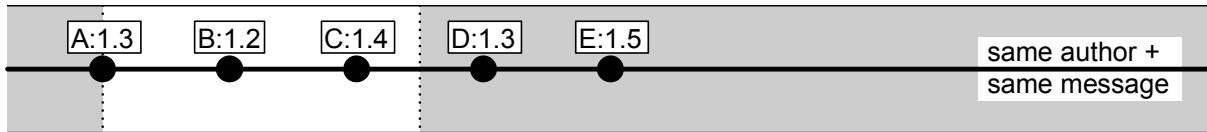


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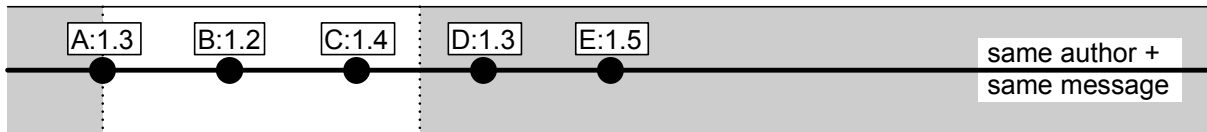
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## Sliding Time Window

$$\forall \delta_i : \exists \delta_j : |time(\delta_i) - time(\delta_j)| \leq T$$



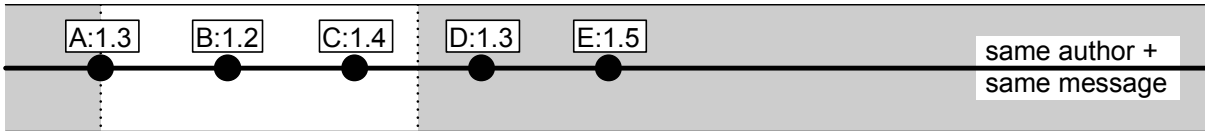


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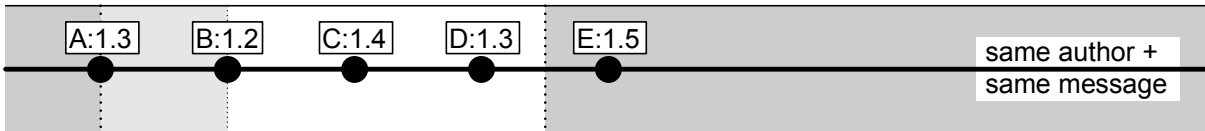
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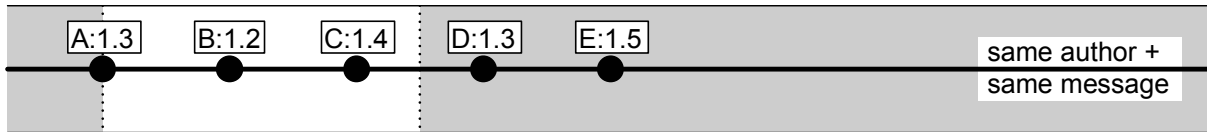


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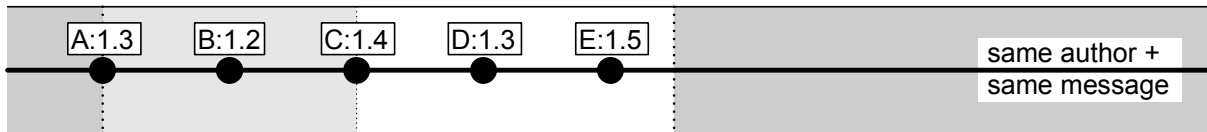
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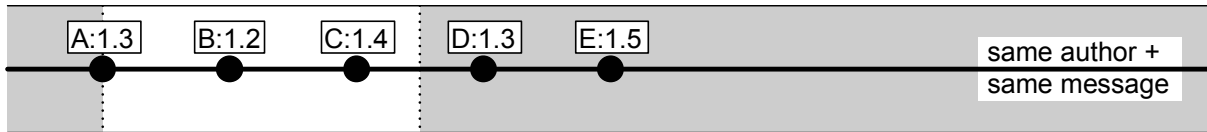


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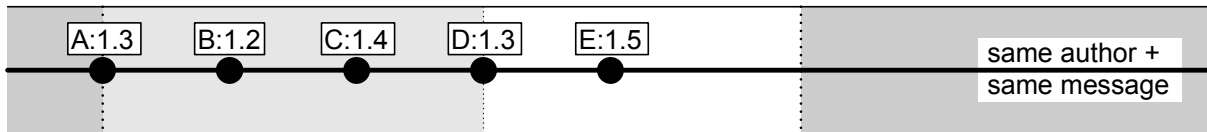
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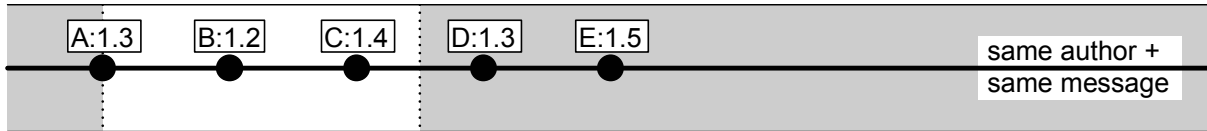


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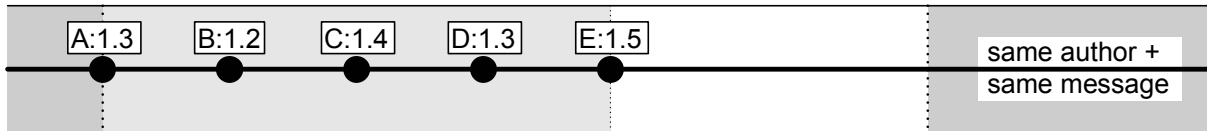
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*All changed files within one transaction have to be different.*





# *Infer Transactions: Commit Mails*

---

All changes listed in a commit mail belong to one transaction.

```
CVSROOT: /cvs/gcc
Module name: gcc
Changes by: zack@gcc.gnu.org 2004-05-01 19:12:47
```

```
Modified files:
gcc/cp          : ChangeLog decl.c
```

```
Log message:
* decl.c (reshape_init): Do not apply TYPE_DOMAIN to a VECTOR_TYPE.
Instead, dig into the representation type to find the array bound.
```

```
Patches:
http://.../cvsweb.cgi/gcc/gcc/cp/ChangeLog.diff?...&r2=1.4042
http://.../cvsweb.cgi/gcc/gcc/cp/decl.c.diff?...&r2=1.1204
```

Commit mails for GCC: <http://gcc.gnu.org/ml/gcc-cvs/>

Not every project provides useful commit mails.





# ***Infer Transactions: Evaluation***

---

We inferred transactions for 3 years GCC using commit mails.

## **Maximal Duration of a Commit**

21:17 minutes for “merged with ra-merge-initial” (5,910 files)

⇒ Sliding time windows are superior to fixed ones.





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## **Maximal Distance between two subsequent Checkins**

Depends on file size, RCS file size, and # of revisions.

For almost all files below 3:00 minutes. Two exceptions:

`gcc/libstdc++-v3/configure`, `gcc/gcc/ChangeLog`

⇒ Time windows should be at least 3:00 minutes.





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## **Minimal Distance between two similar Commits**

Bad news: 0:02 minutes for “Mark ChangeLog”

Good news: All similar commits were really related.

⇒ Time windows have no upper bound (no duplicate files!)





# Detect Fine-Grained Changes

---

What building blocks (e.g., functions, classes, sections, etc.) have been changed between two revisions?

Rev.  $r_1$

```
void A(){
...}
void B(){
...}
void C(){
...}
void D(){
...}
void E(){
...}
```

Rev.  $r_2$

```
void A(){
...}
void F(){
...}
void B(){
...}
void D(){
...}
void E(){
...}
```

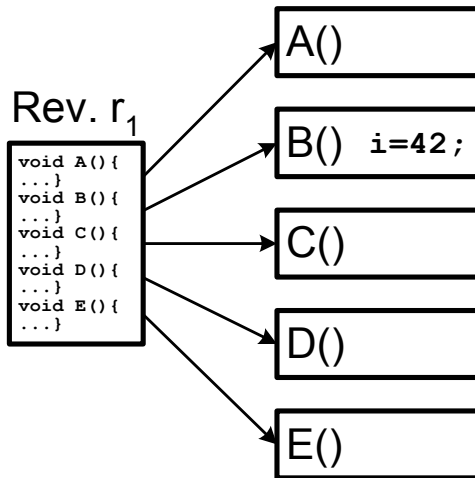


# Detect Fine-Grained Changes

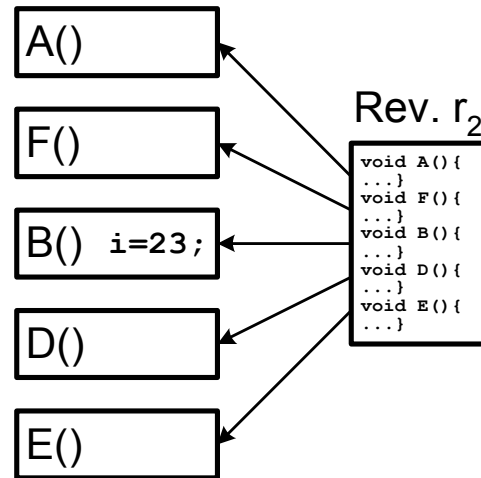


What building blocks (e.g., functions, classes, sections, etc.) have been changed between two revisions?

1. Parse  $r_1$  for entities



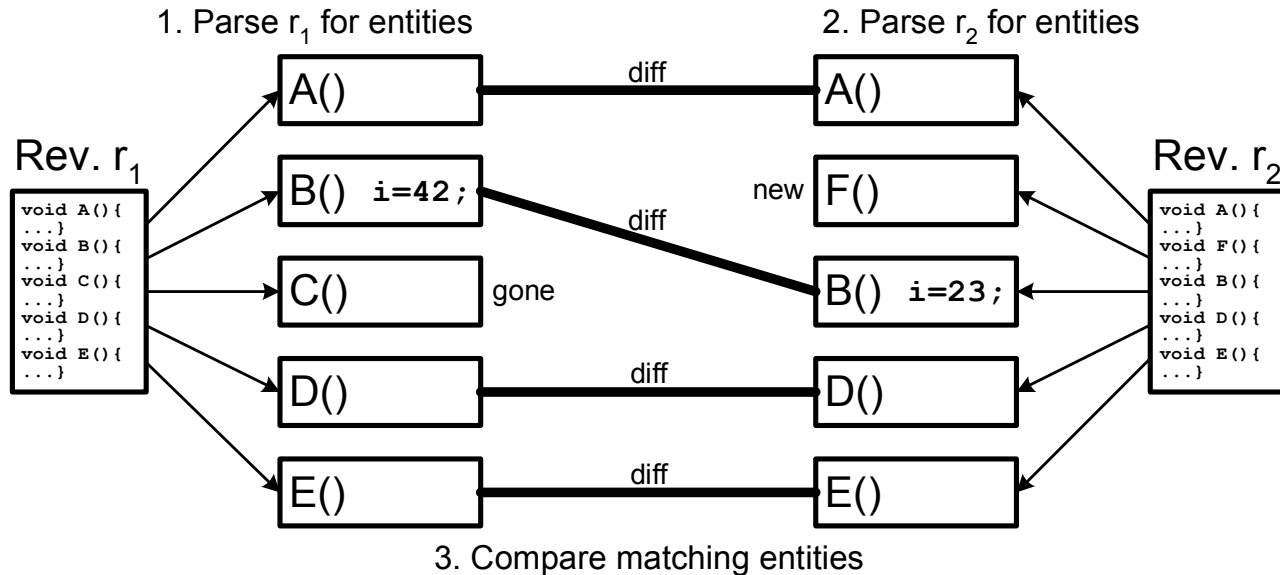
2. Parse  $r_2$  for entities



# Detect Fine-Grained Changes



What building blocks (e.g., functions, classes, sections, etc.) have been changed between two revisions?





# Noise: Large Transactions

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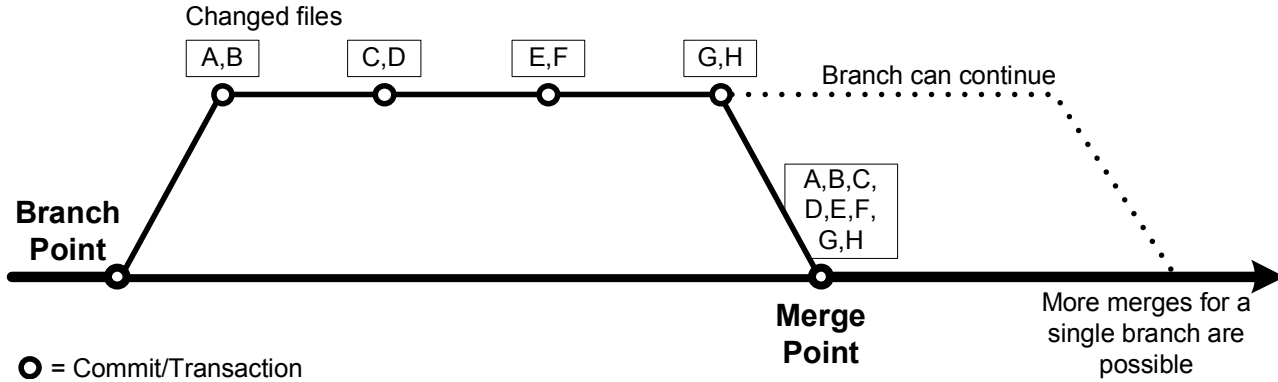
Large transactions are usually outliers:

- “Change #include filenames from <foo.h> *[sigh]* to <openssl.h>.” (552 files, OPENSSL)
- “Change functions to ANSI C.” (491 files, OPENSSL)

**Solution:** Ignore all transactions with size above N.

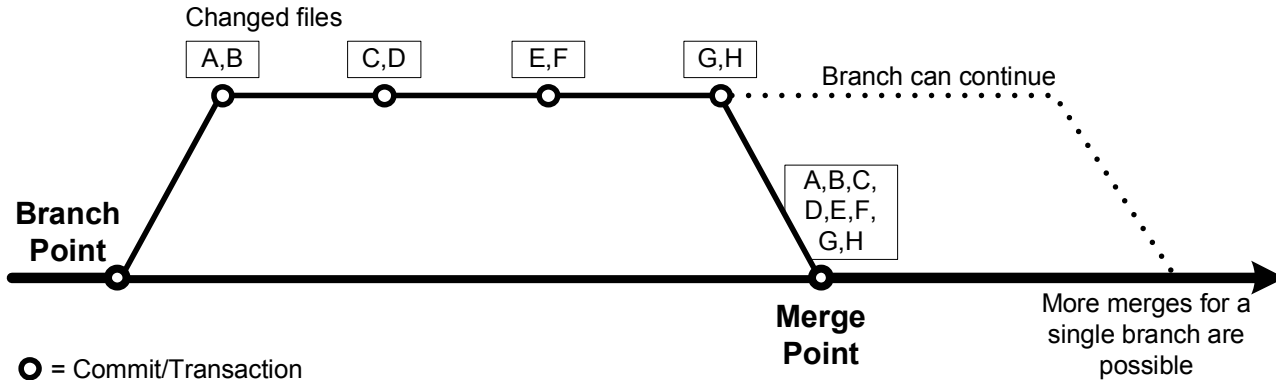


# Noise: Merge Transactions





# Noise: Merge Transactions



Merges are *noise* for two reasons:

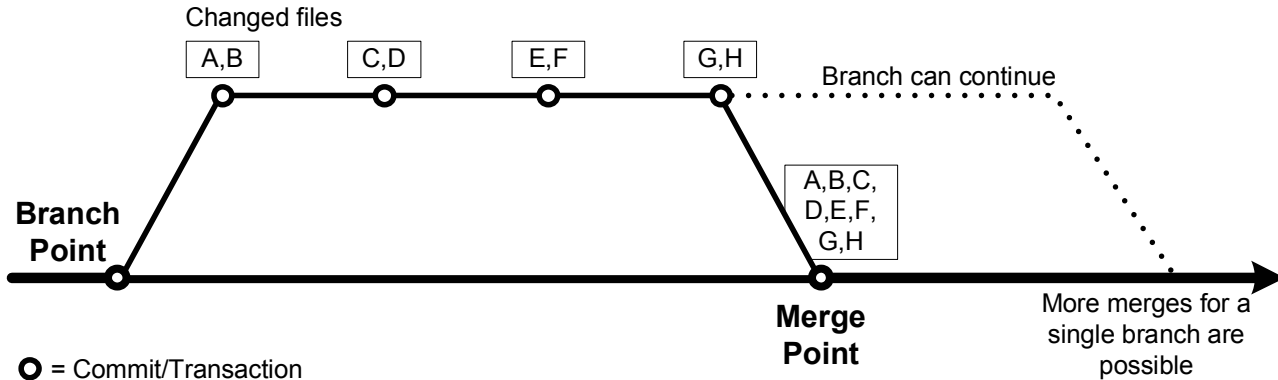
1. Merges contain unrelated changes — e.g. *B* and *C*
2. Merges duplicate related changes — e.g. *A* and *B*



# Noise: Merge Transactions



9/10



## Two Solutions:

- The Fischer/Pinzger/Gall heuristic (ICSM 2003).
- Suspect & Verify approach based on log messages.

*Problem:*

“New `isMerge()`, `isMergeWithConflicts()`, and ...”





# Lessons Learned

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- ★ Databases simplify the exploration of CVS.
- ★ Sliding time windows are superior to fixed ones.
- ★ Length of time windows should be within 3 and 5 minutes.
- ★ Fine-grained analyses are feasible and worth while.
- ★ Take a look at the ECLIPSE framework for comparing files:  
`org.eclipse.compare.structuremergeviewer`
- ★ Merges are dirty transactions and difficult to recognize.

*Preprocessing is the key to any good and reliable analysis.*

